Illinois Autonomous and Connected Track (I-ACT) and The Future of Mobility

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Smart Transportation Infrastructure Initiative













Illinois Autonomous and Connected Track (I-ACT)





Building on Established, Successful Models: I-ACT Mends the Gap for High-speed Connected and Autonomous Trucks



Illinois Autonomous and Connected Track (I-ACT)

Pool of expertise from top-tier universities A clear opportunity for advancing the Nearby access to transportation agenda of the United States multimodal transport (road, air, rail) S С IP **Controlled and** Freight logistics at real settings high-speed with four (fastest loop) seasonal variations Academia Government (R) 🚱 🚱 🌶 **Drones and** I-ACT **3D mobility** Leadership Non-Profit Large-scale Industry **Organization** effort for V2I (instrumented *infrastructure*) ER A platform investment that covers all the basis **Agricultural** of upcoming transportation needs related to **smart** machines and **Fastest computing** and 3D mobility, alongside economic and **5G** market road use and top data workforce development Connectivity analytics (NCSA) **5 T D D**

| | I-ACT | ACM | Mcity | SMARTCenter | SunTrax | Smart Road |
|--|---------------------------------------|---|------------------------------|--------------------------------|---------------------------------------|---------------------------------------|
| State | Illinois | Michigan | Michigan | Ohio | Florida | Virginia |
| Use | Freight & multimodal logistics | Testing, development, & validation | Smart city | Urban network and intersection | Testing, development, & validation | Testing, development, & validation |
| Management | Partnership | Non-Profit | U-M | Non-Profit | Florida | Virginia Tech |
| Academia, Government, Industry, & Non-Profit Partners | ✓ | ✓ | \checkmark | ✓ | ✓ | √ |
| Vehicle calibration and dynamics | \checkmark | Ready to provide a large-scale V2V/V2I/V2X testing arena and spearhead autonomous and connected transportation policies | | | | |
| Small vehicle (car and shuttle) | \checkmark | | | | | |
| Freight | \checkmark | \checkmark | | \checkmark | ? (In construction) | \checkmark |
| Highway speed ≥ 65 mph | 75 | | | 60 | Multimod | al fleet, supply |
| V2V, V2I, & V2X Research | V2V, V2I, V2X | Infrastructure a | and V2V, V2I | V | 2 (in co nstruction) | |
| Multi-platform test facility | Three-lane highway and arterial roads | energy harvest | ing compus and small city | Six-I Distribution | (In construction) | Limited surface street |
| Data management & real-time analytics | NCSA | \checkmark | \checkmark | | (In construction) | \checkmark |
| Four seasons | \checkmark | \checkmark | 1 | Vehicle | × | \checkmark |
| Urban & suburban setting | New infrastructure | | Existing | Synergy | (struction) | Existing |
| Interstate setting | \checkmark | New CAV tech | nology ess freeway | 0-0 | ((('))) | Х |
| Instrumented infrastructure (including pavement, tunnel, & bridges) | ✓ | and retrofitting vehicles | existing affic flow | Conne | ectivity X V2 | X telematics |
| Loop track | \checkmark | \checkmark | X | X | a | nd analytics |
| Tunnel and bridge | \checkmark | \checkmark | | | × | × |
| Controlled climate module | \checkmark | | | | | × |
| Agricultural land & market roads | \checkmark | | | | | × |
| Drone testing | \checkmark | | | | | Х |
| Nearby multimodal facilities (grid-system network, rail, and airport) | \checkmark | | | | | Х |

Collaborative opportunities to invest and utilize the I-ACT testing arena

Performance Testing Private entity provides product to advance development, feasibility, commercialization, and deployment Founding Member Entity invests in testing arena, motivated by long-term economical and/or social benefits

Team Research & Development Sponsor provides funds and collaborates with research team; tasks may include technology and/or protocol development

Academic Research Sponsorship Sponsor involvement is strictly monetary, funding research to perform all tasks

Technical Support Entity or company leases a portion of the track or testing arena to use according to specific needs



Autonomous Truck Platooning











Potential Challenges for Platooning

Vehicle density may compromise free flow speeds



Potential Challenges for Platooning

Possible conflicts near entry and exit ramps

Platoonability of Illinois Roads

IDOT GIS data were analyzed considering traffic density and possible conflicts per 20-mile segments.

Platoonability of Illinois Roads

Roads are divided into 5 platoonability levels with level 3 being the threshold for platoonability. 89% of interstates are platoonable during peak hours

Pavement Damage and Platooning

Scenario 1 – Channelized Traffic

- Trucks always follow the same path on the pavement
- Most damaging to system due to load concentration
- Platooning is more damaging than traditional traffic in this

scenario

Pavement Damage and Platooning

Scenario 2 – Local Optimization

- Trucks follow each other with slight offset
- Decreases the damage by decreasing load concentration
- However, increases fuel consumption by increasing

drac

Pavement Damage and Platooning

Scenario 3 – Centralized Optimization

- Each platoon follow a specified path
- Path is selected and communicated to platoon by a centralized optimization policy
- Optimizes fuel savings and pavement damage at the same time

Platooning: a Challenge to Opportunity

and Aerodynamics

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